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System-Theoretic Likelihood and Severity Analysis for Safety and Security Co-Engineering

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Safety and Security

- Safety and Security
 - Represented by separated communities in both industry and academia
 - Issues have been considered separately during the system design



Safety and Security Co-Engineering

- Information technologies and communication devices are increasingly being integrated into modern control systems
 - Easily discovered once connected to the Internet
 - Vulnerable to cyber attack, causing physical impacts
- Security vulnerabilities exploited to compromise the safety critical systems, leading to financial losses and in some cases, human injures or death
- Usually, it is a matter of time before security flaws are discovered and exploited even in well engineered critical systems



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Example: Automated Metro Train





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Example: Automated Metro Train

- An intermittent failure of the signalling hardware on a single train
 - The cause for the loss of signalling communications of other trains on Circle Metro Line
 - The safety feature, emergency brake, being automatically activated





Example: Automated Metro Train



Could such an event be replicated maliciously?



Exploit Safety Features (e.g., Emergency Braking) to cause large-scale service disruptions



Safety and Security Co-Engineering

- Therefore, it is becoming increasingly important to address the combination of safety and security in modern control systems.
- A transformation among safety and security communities to work together especially in risk assessment
- A growing body of work relating to safety and security co-analysis methods



Safety and Security Co-Engineering Method (SAHARA)



ISO 26262- Hazard Analysis and Risk Assessment (HARA)

Used in a conventional manner to classify the safety hazards according to the Automotive Safety Integrity Level (ASIL) STRIDE method

Used to model the attack vectors of the system

Security Aware Hazard Analysis and Risk Assessment (SAHARA)

Security threats that may violate the safety goals are considered for the further safety analysis

Safety and Security Co-Engineering Method (FMVEA)



Integration through the combination of a conventional **safety risk assessment method** and a **variation** of the conventional safety risk assessment method (incorporating threat information based on the STRIDE model) for security risk assessment



Safety and Security Co-Engineering Method (FACT Graph)



Integration through the combination of a conventional safety risk assessment method and a conventional security risk assessment method



Analysis Methods for co-engineering

- Traditional component-centric methods
 - Design-stage risk assessment
 - E.g., fault/attack tree, failure mode and effect analysis (FMEA/FMVEA)
 - Challenging to deal with complex interactions among safety critical systems
- System-Theoretic Process Analysis for Security approach (STPA-Sec)
 - Emphasis on control loop, emergent system behavior
 - Limitations: not provide guidance on how to address the identified scenarios



Our Approach Overview

- A new hybrid method, Systems-Theoretic Likelihood and Severity Analysis (STLSA)
 - Top-down view of functional control structure of a system
 - Threat and failure scenarios with a semi-quantitative risk rating system
- Contributions
 - Leverage advantages of STPA-Sec (System-centric method) and FMVEA (Component-centric method)
 - A case study applying our proposed method, STLSA on a realistic train braking system



Original Methods – STPA-Sec

• STPA-Sec

- Extension of the System-Theoretic Process Analysis (STPA) from safety community
- Derived from the System-Theoretic Accident Modeling Process (STAMP)
- Motivation
 - Considering the impact of cyber security on system safety from a *"strategic"* rather than a *"tactical"* perspective
 - Taking a *top-down* analysis approach focusing on the *functionality* provided by a system, and its *functional control* structure
 - Rather than focusing on threats and attacker properties such as intent and capability



Original Methods – STPA-Sec

- Delivery
 - A list of control actions in the system that may be unsafe/insecure
 - How those control actions may lead to unacceptable losses in one or more causal scenarios
- Gap
 - Not evaluate the relative likelihood or severity of impact for those causal scenarios
 - Not fully aligned with current safety/security standards



Original Methods – FMVEA

- FMVEA
 - Extension of the widely-used FMEA (Failure Mode and Effect Analysis)
 - Security related information, i.e., vulnerabilities, threat modes, and threat effects

FMVEA Process

- 1. Divide a system into components
- 2. For each component, identify failure modes and/or threat modes
- 3. Identify the effect of each failure and/or threat mode (includes attack probability)
- 4. Determine severity of the final effect
- 5. Identify potential causes / vulnerabilities / threat agents
- 6. Estimate frequency or probability of occurrence for the failure/threat mode during the predetermined time period

7. Steps 3-6 repeat until there are no more failure modes/vulnerabilities or components left to analyze

Original Methods – FMVEA

- Component-centric analysis method

 Based on component failure
- Challenges
 - Scalability: For large systems, it's not sufficient to consider lower level failures and threats (especially those with complex interactions or emergent behaviour)
 - Multiple failures: It's far more plausible in a deliberate attack
 - System effect is not made explicit





STLSA Combination

- Combine desirable characteristics
 - Component-centric approach
 - System-centric approach
- Systems-Theoretic Likelihood and Severity Analysis (STLSA)





A Hybrid Method of STLSA



STLSA Process

- Start with an STPA-Sec analysis
- With a number of ways in which several aspects are enhanced to better address complex interactions.
- More details are shown in the context of our case study
 - Functional control structure
 - System
 - Environment
 - Multiple instances of actors & components in the system.
 - Extended guide word analysis for intentional scenarios





Case Study- Control Model

STLSA-Rating System

STLSA-Rating System

From STPA-Sec process Safety cause mode Frequency score failure failure Suggested in EN 50126-1 mode cause Inferred by effect functional 6-tier, ranging from highly control structure threat improbable (1) to frequent (6)vulnerability mode threat agent From EN severity Likelihood: probability 50126-1 Security ^[1] Safety System susceptibility From EN 50126-1 How easy it is for a potential Security criticality Reachability + Uniqueness adversary to connect to and Common between acquire knowledge about the failure (safety) and threat system (security) modes

[1] C. Schmittner, T. Gruber, P. Puschner, and E. Schoitsch. Security application of failure mode and effect analysis (FMEA). In SAFECOMP, pages 310{325.Springer,

2014.

0 = no network

private network

3 = public network

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I = temporary connected

2 = normal private network,

= restricted

3 = standard

2 =commercially available

Case Study – Train Braking System

- Train Braking System Overview
 - Most safety-critical subsystem
 - Service and emergency braking processes
 - Multiple process of activating/controlling various braking actions, shared components
 - Complex safety and security challenges inherent in this system
 - Incident 1: Oil leakage on the track
 - Incident 2: Signalling interference from a nearby train

Case Study- System Description

- A typical train
 - Three cars
 - Overlays the key components of braking system
- Service braking
 - Electrical braking
 - Activated in early phase
 - Energy saving purpose, No impact to train operation, fully compensated by frictional braking
 - Frictional braking
 - Activated at mid speed
 - Train operation will be affected if frictional braking fails to be conducted properly
- Emergency braking
 - Emergency braking loop
 - Frictional brake with full braking force

Train Car

Motor Car

Case Study- Control Model

- Identify main entities
 - Automated controllers
 - Cyber and physical components
 - Human factors
- Control loops
 - Interactions among entities
 - Controllers -> Controlled process: actions/commands
 - Controllers <- Controlled process: feedback/responses</p>
 - Flaws/inadequacies in control loops could possibly lead to unsafe control actions and hazardous states

Case Study-Hierarchical Control Structure

Case Study- Accidents Identification

Identified Accident

A1. Train decelerates or stops in a sudden way, making passengers fall down and

even get injured

A2. Related system or equipment are damaged.

A3. Collision with objects or other trains.

A4. Train stops at wrong places.

- Safety related losses
 - Exclude other losses, e.g., financial/operational
- Examples
 - A1: sequential brake processes fail to connect in an appropriate way
 → train's smooth operation can no more be ensured
 - A2: Regeneration phase of electrical braking → 3rd rail voltage is too high or too low → Damage to traction power system
 - A3: Collision with objects or other trains
 - A4: Stop in the middle of a tunnel/Miss the platform

Case Study-Hazards Identification

Identified Hazards and Corresponding Accidents (in parentheses)

- H1. Coupling between adjacent cars is being compromised.(A2)
- H2. Train is not at the right speed at certain location.(A3, A4)

H2-1. Train is overrun.

H2-2. Train is underrun.

- H3. Substantial phases fail to connect smoothly.(A1)
- H4. Traction power system e.g., 3rd rail, is over voltage.(A2)
- H5. Procedure continues for a prolonged time (A3, A4)

H6. Train does not stop properly (A3)

H7. Braking phases are conducted with unintended timing, in an unintended amount, or at an unintended location (A3, A4)

- Example
 - Individual cars sense weight \rightarrow brake with different force accordingly
 - Corresponding equipment (e.g., BCE, BCU) are dedicated to control the braking process for each bogie
 - Couplings of cars could suffer from excessive extrusion force or separating force
 - Inadequate control in this process (H1) leads to the damage of relevant equipment (A2)

Case Study-Unsafe Control Actions

Linsofa Control Actions	Type	Control	UCA	Unsafe Control Actions	Possible
Olisale Control Actions		Action	No.		Hazards
Contexts under which control	Required	Request	UCA-1	Electrical braking request is not pre-	Non-
actions could be unsafe and lead to	Action	electrical		formed by PCE in the train braking sce-	hazardous
hazardous status	Not	braking		nario	
	Performed	Activate	UCA-2	Frictional braking is not activated during	H1, H2-1,
		frictional		the train braking phase	H5, H6
		braking			
	Hazardous	Activate	UCA-3	Inadequate braking force is performed	H1, H2-1,
	Action	frictional		and transmitted to downstream braking	H5, H7
	Per-	braking		units in frictional braking phase	
	formed				
	Incorrect	Activate	UCA-4	Pneumatic control isn't properly be ap-	H3, H7
All the control loops in	timing or	pneu-		plied at the mid of speed to compensate	
	order	matic		for the decrease in electrical break effort	
nierarchical control		control			
structure are reviewed	Incorrect	Activate	UCA-5	Electrical braking is preformed too long,	H4
	Duration	electrical		and fails to stop before traction power sys-	
		braking		tem has been fully regenerated.	

4 types of UCA (STPA-Sec)

Case Study – Intentional/Unintentional **Causal Scenarios**

	_	"U": Unintentional scenari	OS		1.1	. 1.1		
A few possible causal	2	"I " Intentional scenarios				eIII	nood ·	of causal scenarios
scenarios for UCA-3					(5)	ect	cion :	3) Rate "R" and "U"
	ID	Potential Causal Scenarios	Type (U/I)	S	R	U	p/f score	according to train
Exhaustive checklists	A	Sensors or related equipment(e.g. BCE, BCU) mal- function.	·U	1	-	-	5	brake management
\rightarrow A starting point	В	Inadequate control algorithm occur to BCE calcu- lation model, which causes the amount of breaking force is not calculated correctly.	- U s	2	-	-	2	
	С	Unidentified disturbance such as the changes of environment(e.g. the track is oily), makes the braking force in normal circumstance not adequate any longer.	s U	3	-	-	2	 Reachability Internal cyber components Net cyblic eccessible
Common causes calls	D	The feedback path to BCE may be congested inten- tionally, then the train cannot explicitly determine the required brake force for each bogie	- I	2	2	1	3	Not public accessiblePrivate network
for extra attention and efforts	Е	Manufactured braking force amount is sent by BCE to the downstream braking equipment, and that forged message overwrites the legitimate braking force.	I t	3	2	1	3	Uniqueness Most - Restricted
	F	Maliciously tamper or fabricate readings of relevant devices (e.g. oil gauge, sensors) after creating an unsafe situation of environment. ote: Type(U/I)-Type(Unintentional scenario/Intenti	f I onal sc	3 cenar	2 rio); S	2 –Sev	4 verity;	 Process/operations/Se nsors – commercially available

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Assess the severity and

Discussion

- Reconciling perspectives from STPA-Sec and FMVEA
 - A system-level view of unsafe and insecure control actions
 - Greater support for structured risk assessment
 - Grounded in standards such as EN 50126-1 for railway applications
- Safety and Security in the system development lifecycle
 - Ideally starting from beginning (design phase)
 - Operation phase (e.g., our project with Singapore railway operator)
 - System upgrade and improvement
 - System audit

Conclusion

- A new hybrid method STLSA
 - Identify and evaluate safety/security risks
 - Unsafe situations posed by the environment's impact on system control actions, e.g., oil on the track
 - Prioritize high-risk issues for remediation
 - High S and p/f score
- Tool Support
 - A large number of control loops and causal scenarios
 - Assist with creating/maintaining/tracking assessment documentation
- On-going work
 - New plugin in XSTAMPP, an open-source platform for safety engineering designed
 - Support a more comprehensive safety and security coengineering process as proposed in STLSA

Key Reference

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Thank You!

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